

# CT Convolution (1A)

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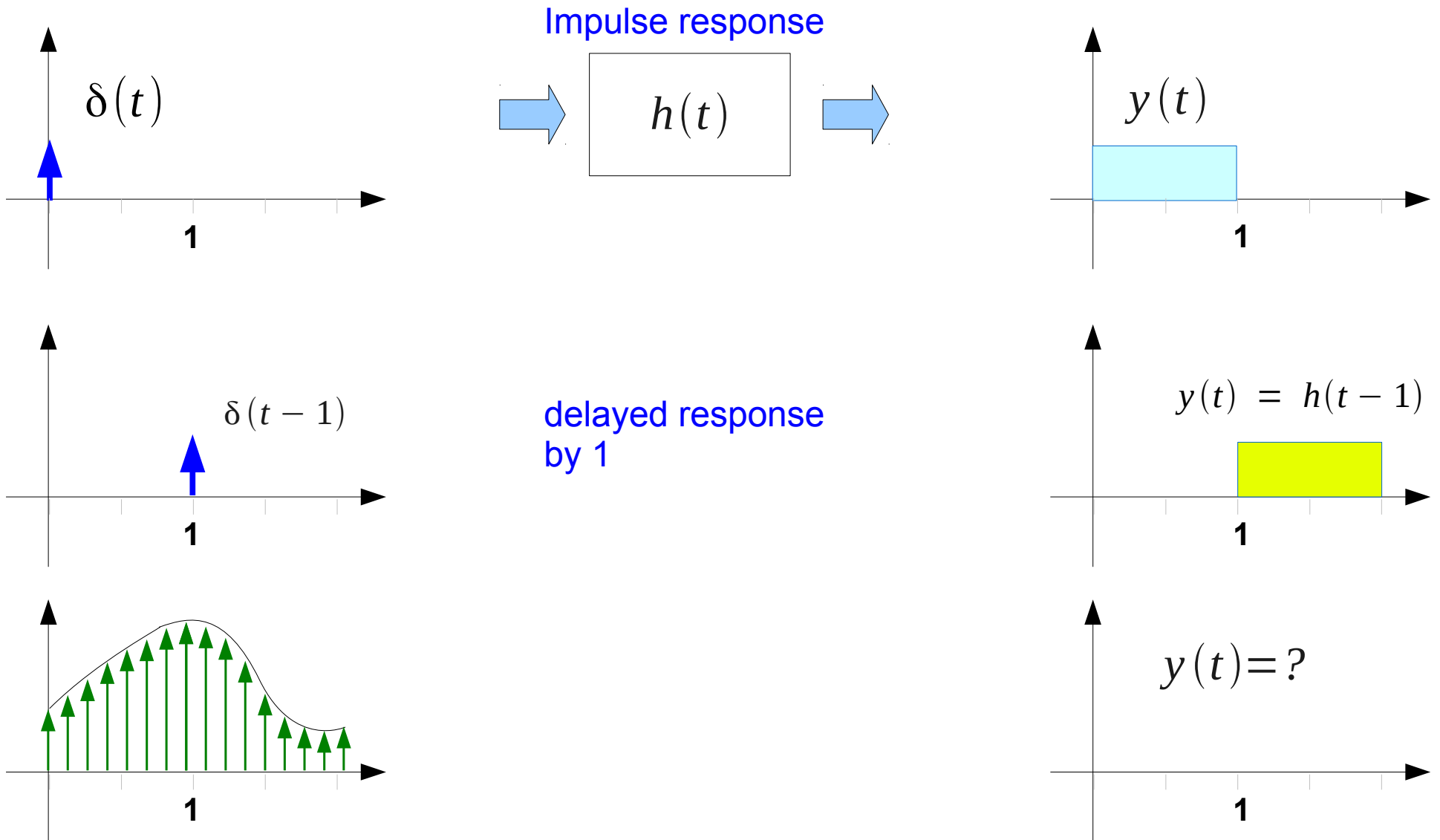
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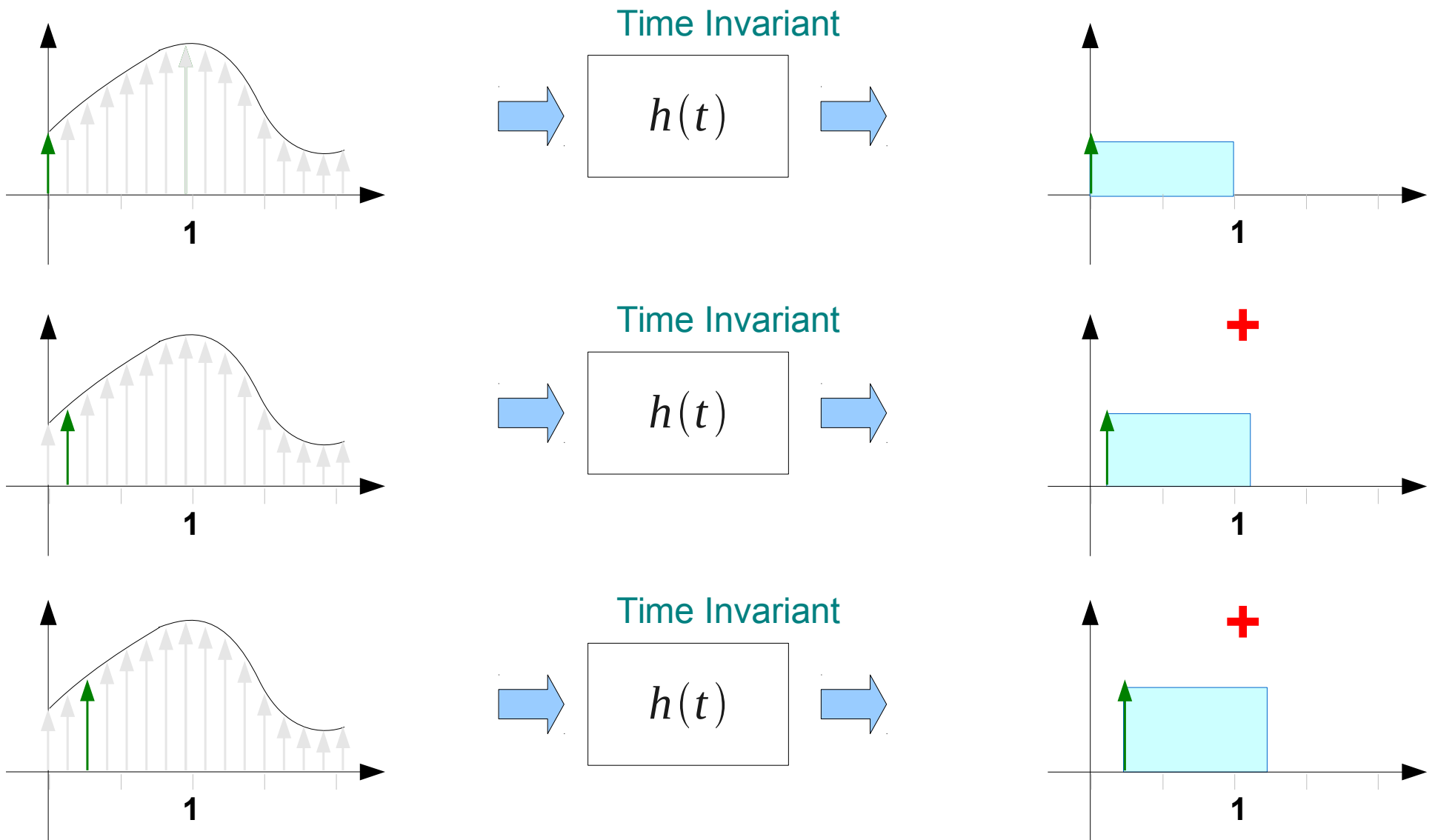
Please send corrections (or suggestions) to [youngwlim@hotmail.com](mailto:youngwlim@hotmail.com).

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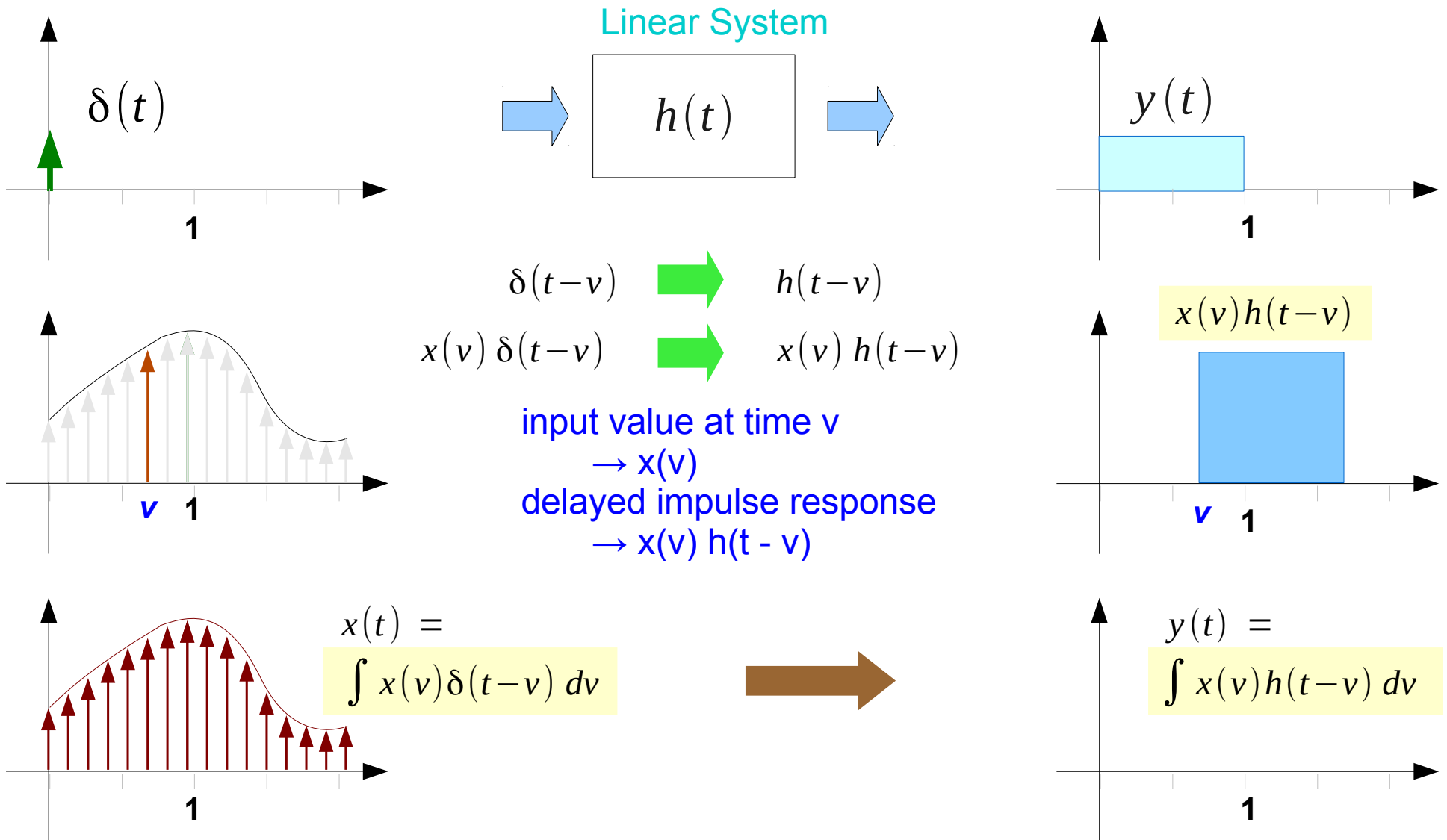
# Convolution: delayed response of $h(t)$ (1)



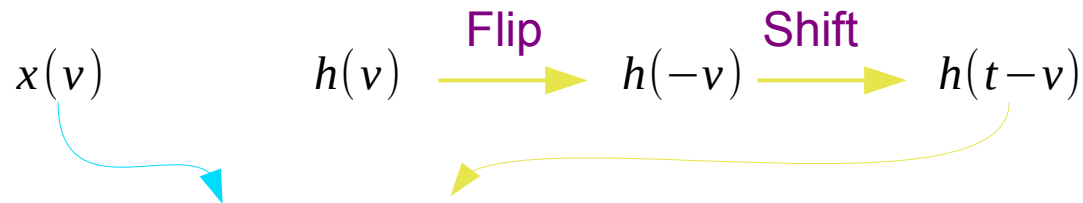
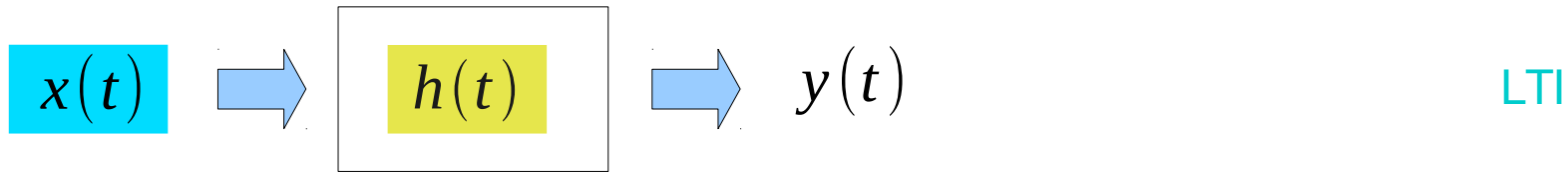
# Convolution: delayed response of $h(t)$ (2)



# Convolution: delayed response of $h(t)$ (3)

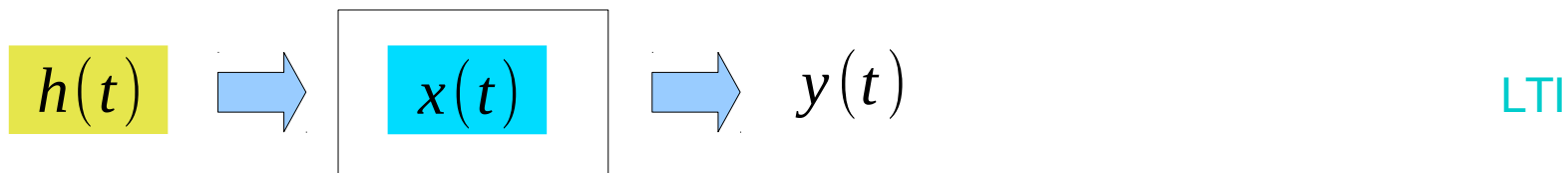
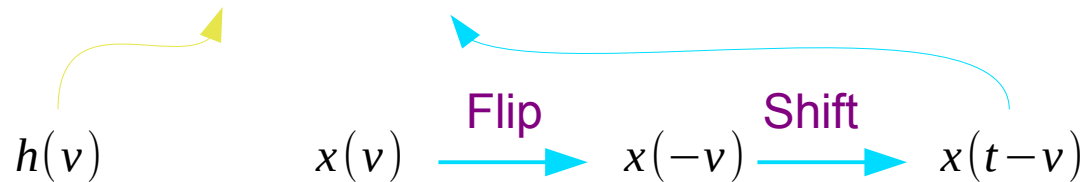


# Convolution: Commutative Law

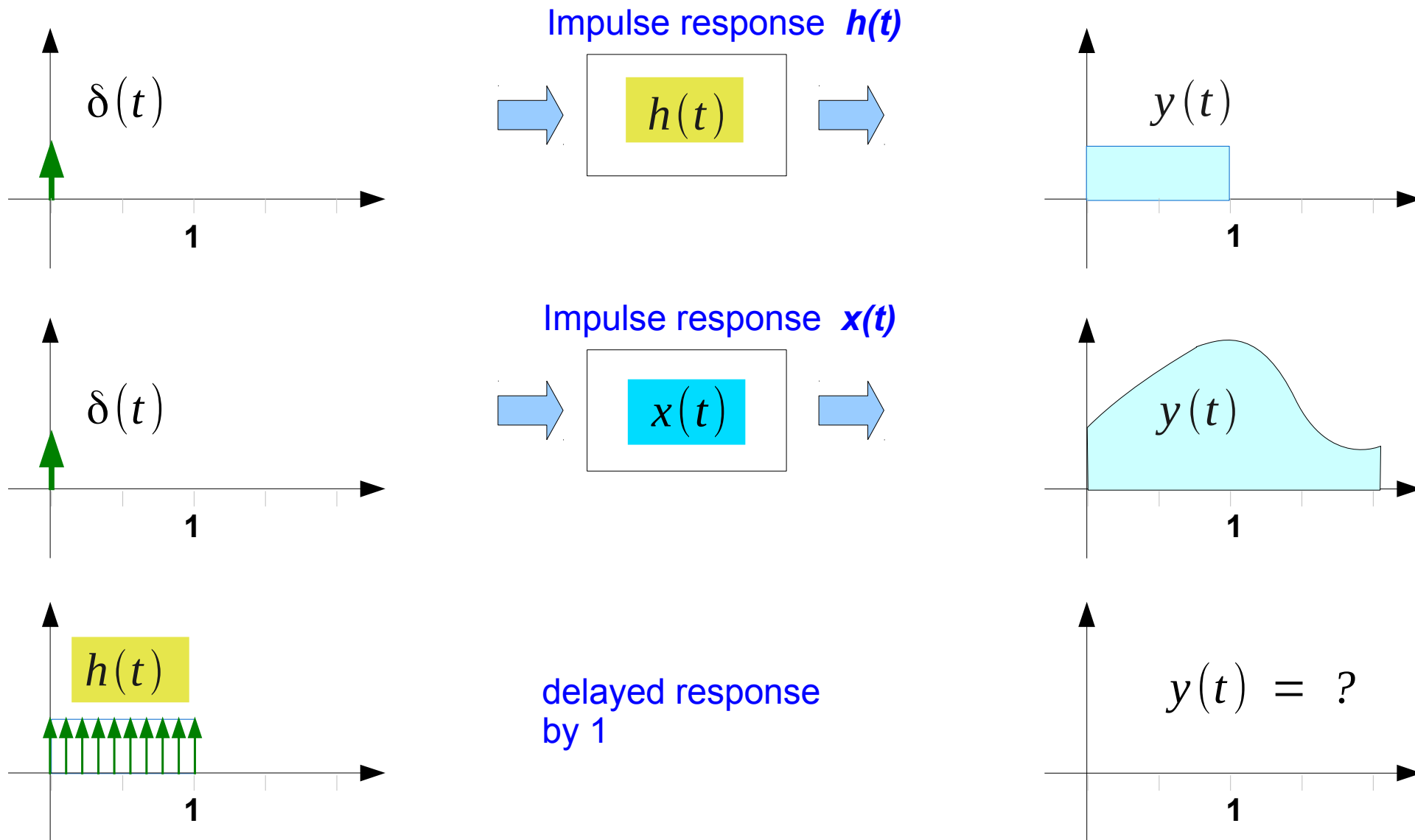


$$\int x(v)h(t-v) dv = y(t)$$

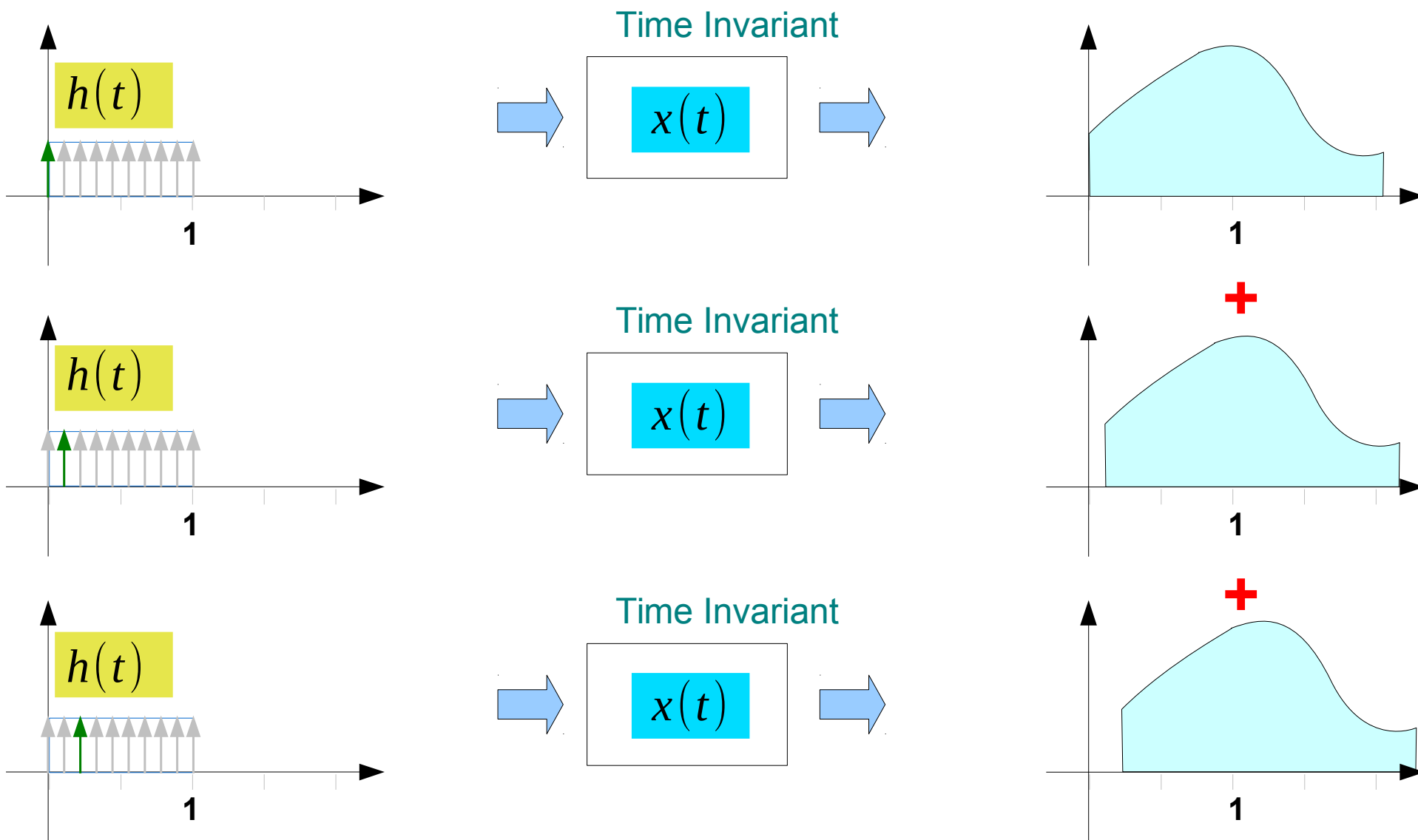
$$\int h(v)x(t-v) dv = y(t)$$



# Convolution: delayed response of $x(t)$ (1)

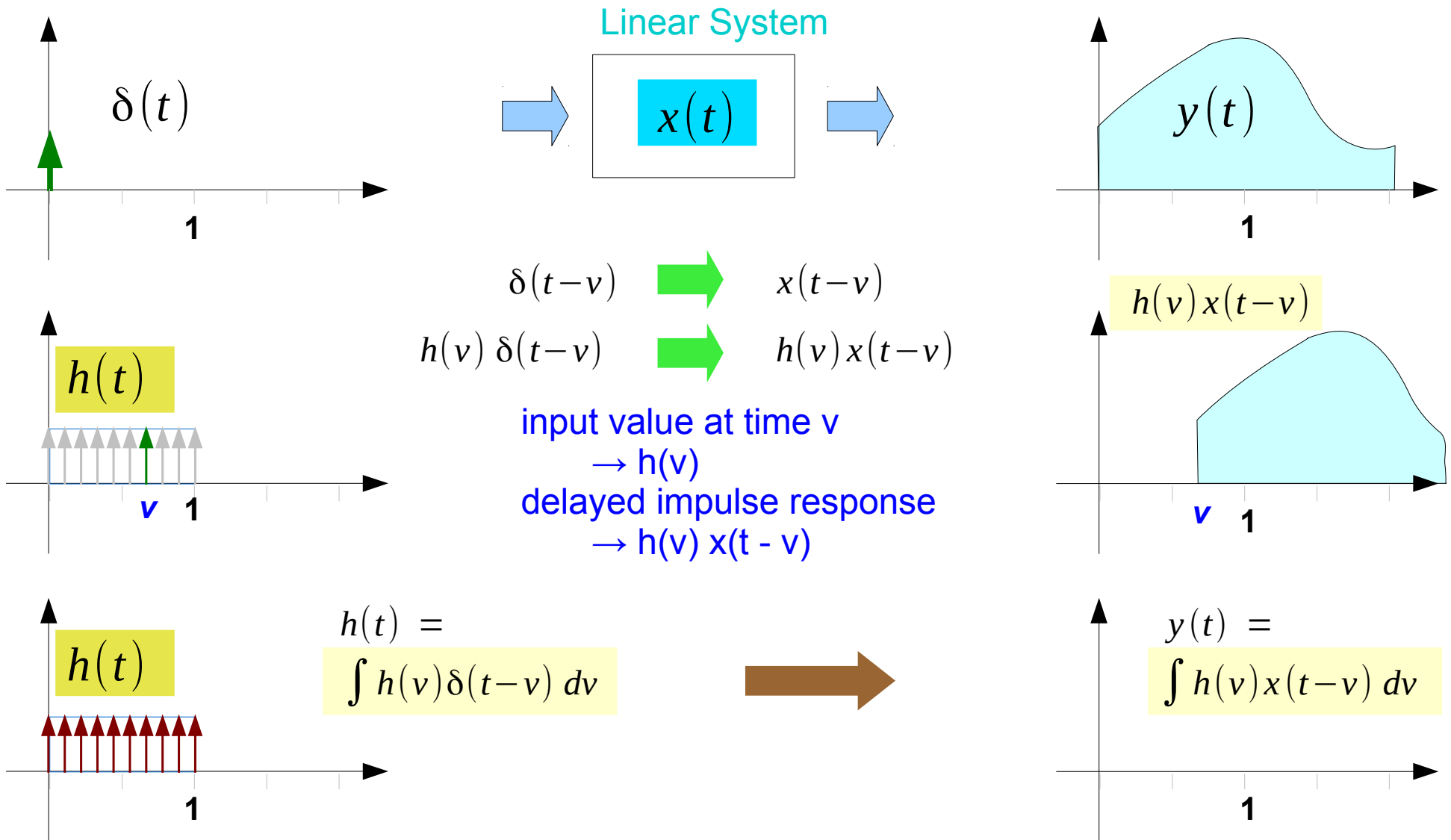


# Convolution: delayed response of $x(t)$ (2)

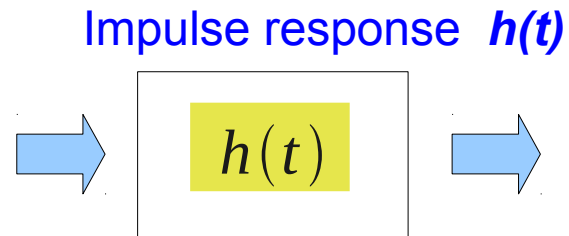
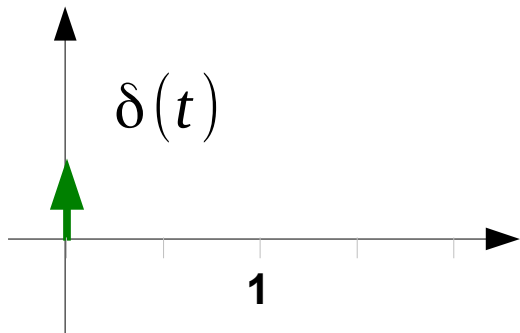




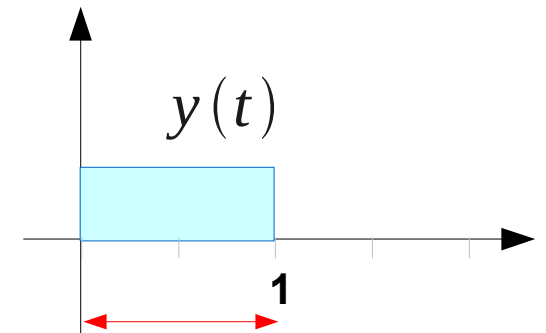
# Convolution: delayed response of $x(t)$ (3)



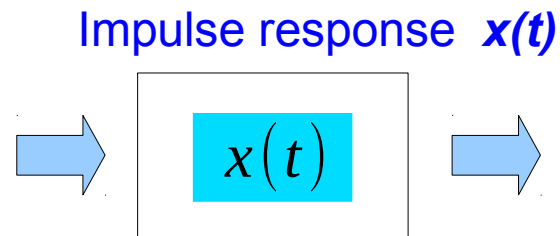
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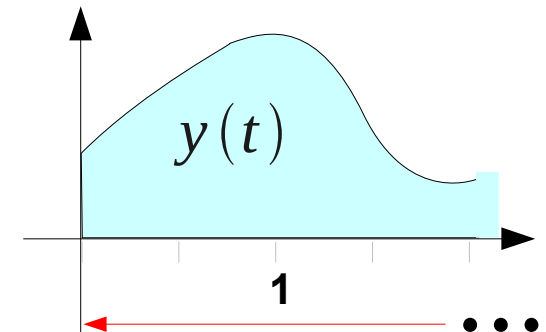
Finite Impulse Response



Finite Duration



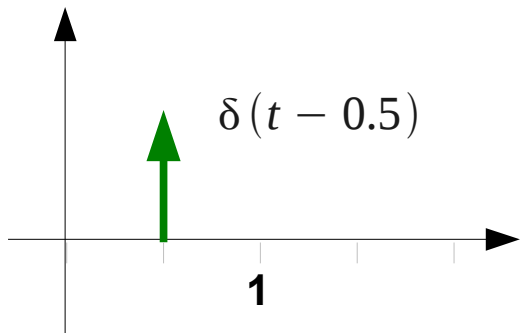
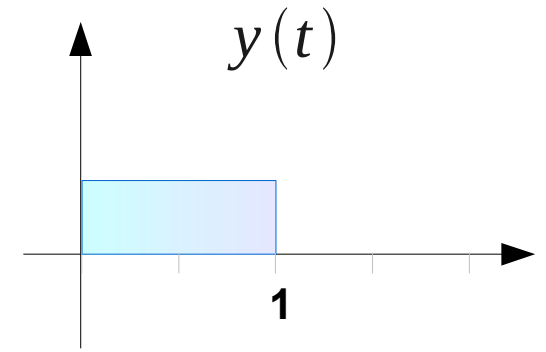
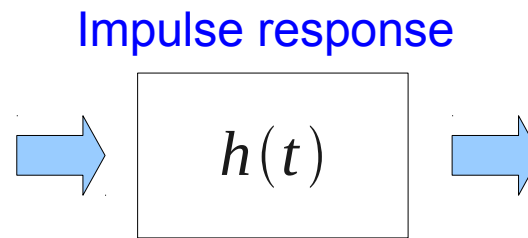
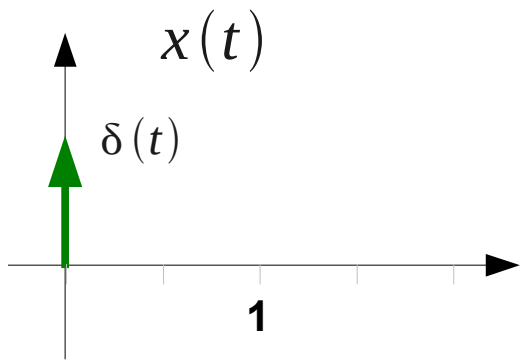
Infinite Impulse Response



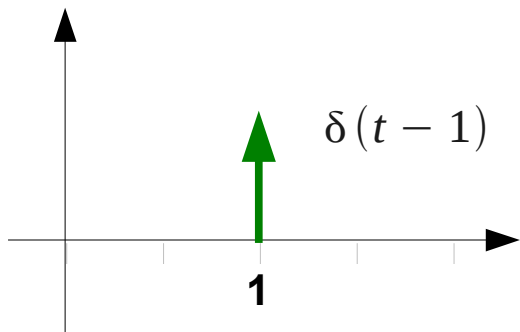
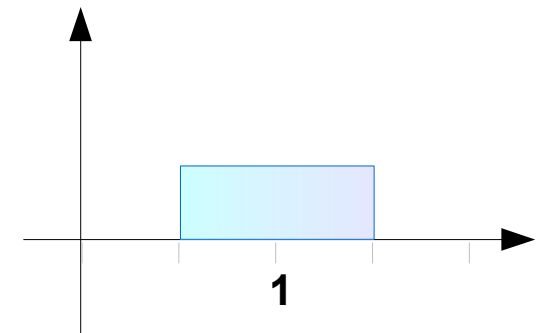
Infinite Duration



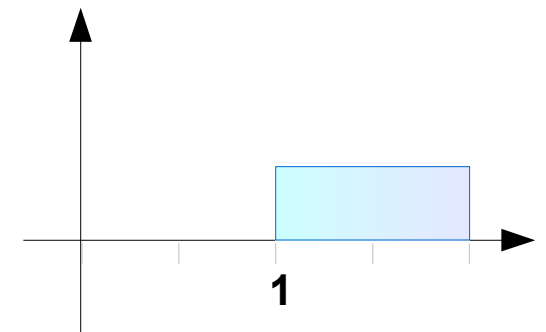
# Impulse Response



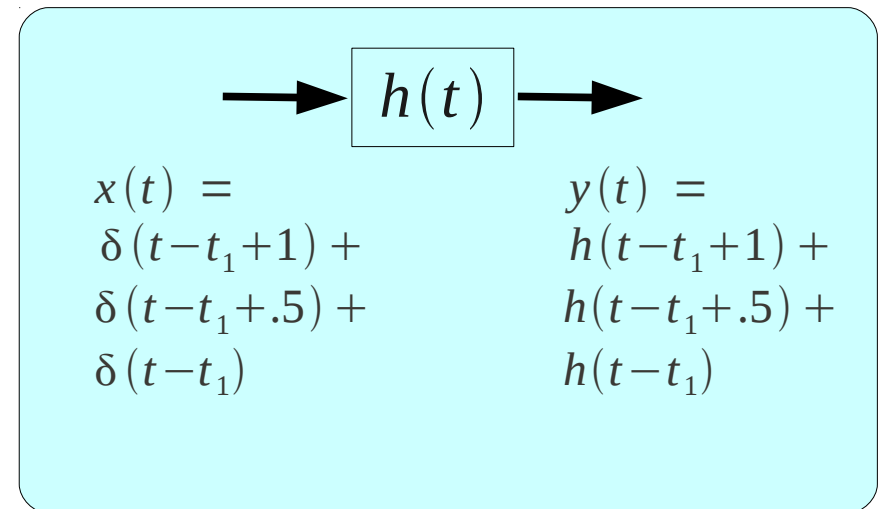
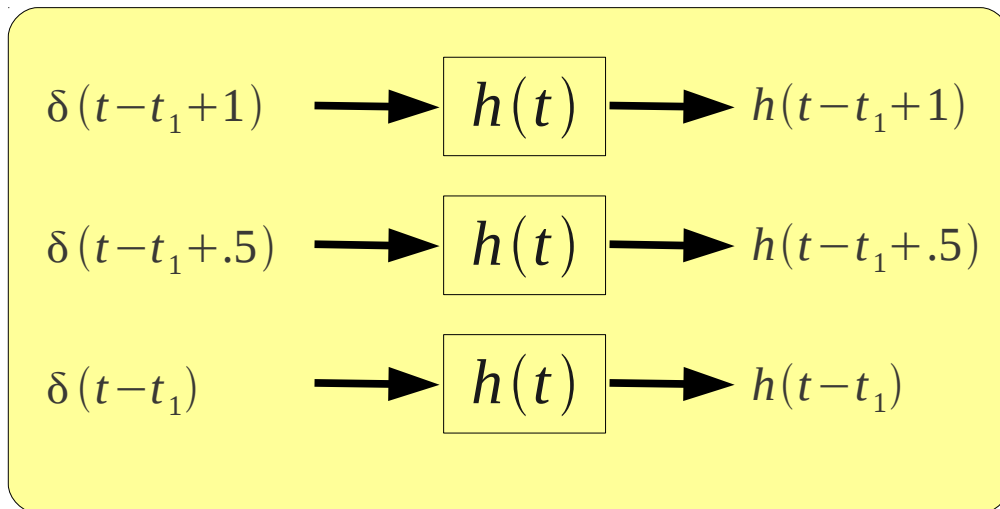
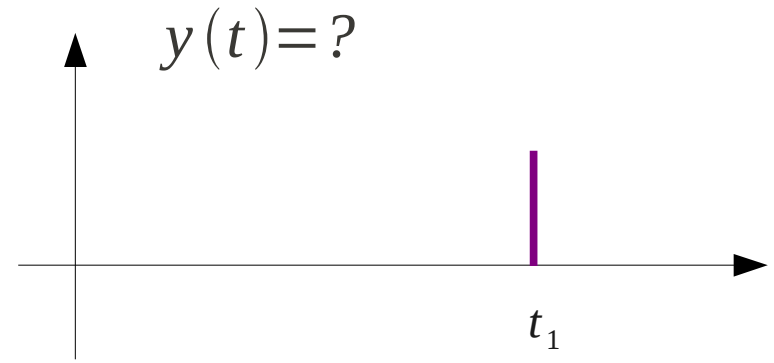
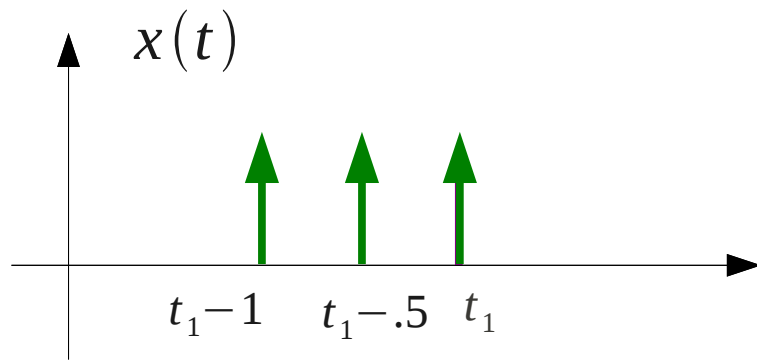
delayed response  
by 0.5



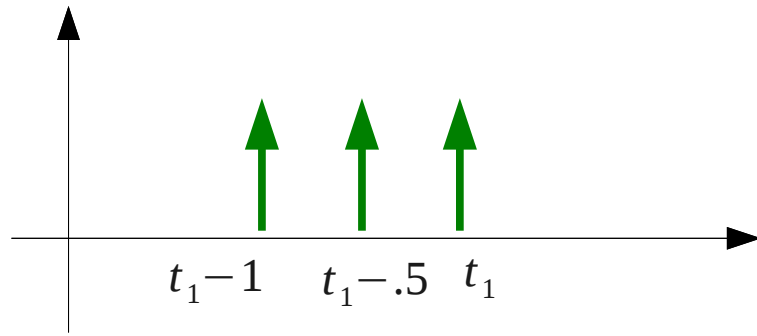
delayed response  
by 1



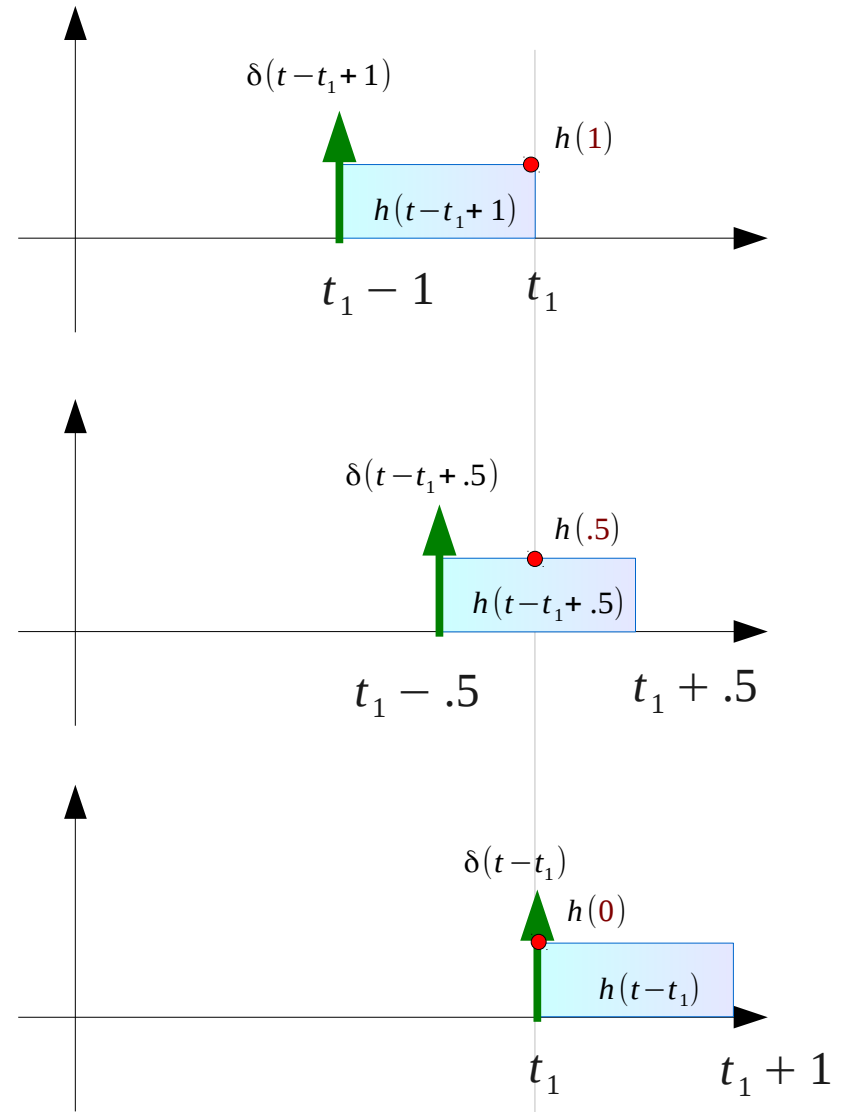
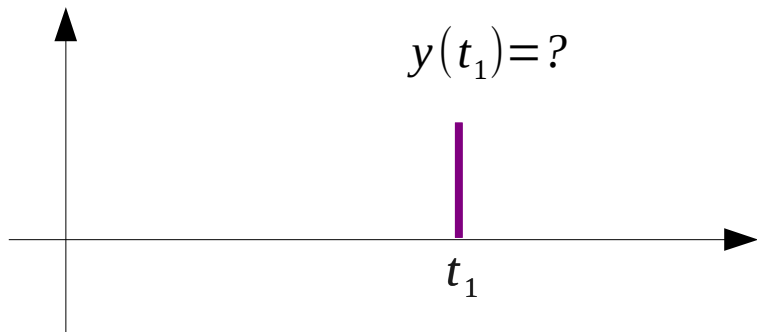
# LTI System



# Computing $y(t_1)$ : Output at $t = t_1$

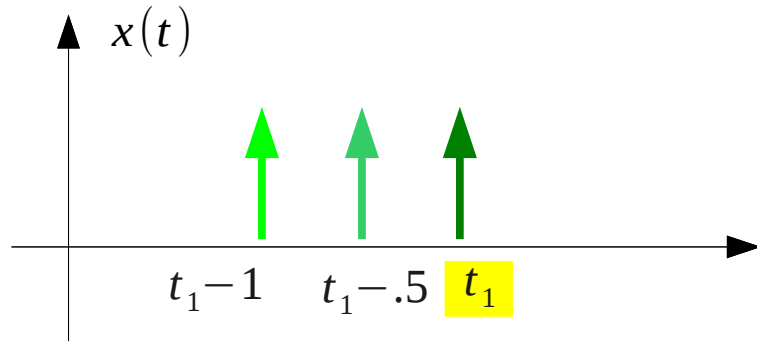


$$x(t) = \delta(t - t_1 + 1) + \delta(t - t_1 + .5) + \delta(t - t_1)$$

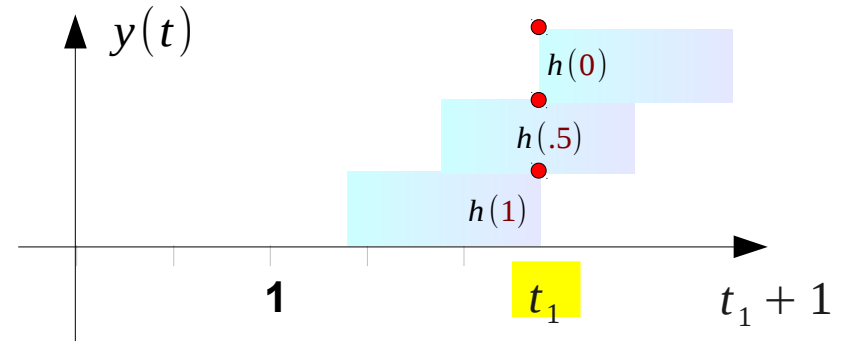
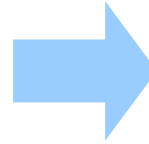


# Computing $y(t_1)$ : delayed impulse response $h(t)$

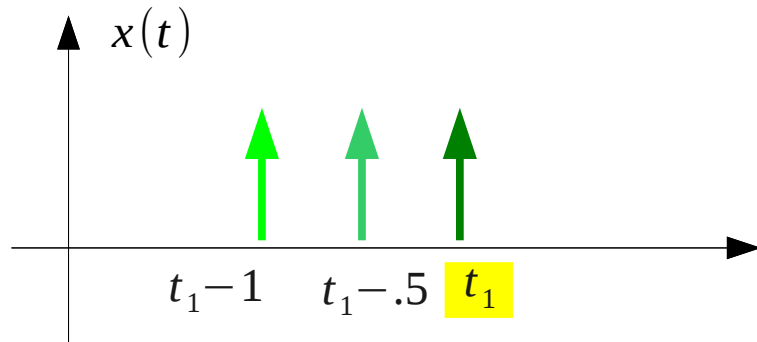
delayed impulse response –  $h(t)$



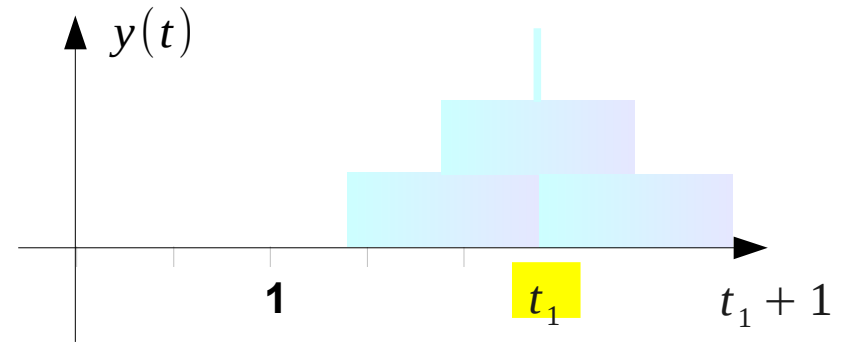
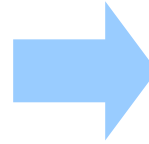
$$x(t) = \delta(t-t_1+1) + \delta(t-t_1+.5) + \delta(t-t_1)$$



$$y(t_1) = h(1) + h(.5) + h(0)$$



$$x(t) = \delta(t-t_1+1) + \delta(t-t_1+.5) + \delta(t-t_1)$$



$$y(t) = h(t-t_1+1) + h(t-t_1+.5) + h(t-t_1)$$

# Computing $y(t_1)$ : flip and shift $x(t)$

$$x(t) = \delta(t-t_1+1) + \delta(t-t_1+.5) + \delta(t-t_1)$$

↓ Change of variables  $t \rightarrow v$

$$x(v) = \delta(v-t_1+1) + \delta(v-t_1+.5) + \delta(v-t_1)$$

↓ Flip around y axis and then shift to the right by  $t$   $v \rightarrow t-v$

$$x(t-v) = \delta(t-v-t_1+1) + \delta(t-v-t_1+.5) + \delta(t-v-t_1)$$

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$$y(t) = \int x(t-v) h(v) dv$$

$$= \int \delta(t-v-t_1+1) h(v) dv \quad \rightarrow h(t-t_1+1) \text{ impulse response delayed by } t_1-1$$

$$+ \int \delta(t-v-t_1+.5) h(v) dv \quad \rightarrow h(t-t_1+.5) \text{ impulse response delayed by } t_1-.5$$

$$+ \int \delta(t-v-t_1) h(v) dv \quad \rightarrow h(t-t_1) \text{ impulse response delayed by } t_1$$

---

$$y(t) = h(t-t_1+1) + h(t-t_1+.5) + h(t-t_1)$$

$$\rightarrow y(t_1) = h(1) + h(.5) + h(0)$$



# Computing $y(t_1)$ : flip and shift $h(t)$

$$h(t)$$



Change of variables

$$t \rightarrow v$$

$$h(v)$$



Flip around y axis and then shift to the right by  $t$

$$v \rightarrow t-v$$

$$h(t-v)$$

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$$y(t) = \int x(v)h(t-v) dv$$

$$= \int \delta(v-t_1+1)h(t-v) dv \rightarrow h(t-t_1+1) \text{ impulse response delayed by } t_1-1$$

$$+ \int \delta(v-t_1+.5)h(t-v) dv \rightarrow h(t-t_1+.5) \text{ impulse response delayed by } t_1-.5$$

$$+ \int \delta(v-t_1)h(t-v) dv \rightarrow h(t-t_1) \text{ impulse response delayed by } t_1$$

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$$y(t) = h(t-t_1+1) + h(t-t_1+.5) + h(t-t_1)$$

$$\Rightarrow y(t_1) = h(1) + h(.5) + h(0)$$

# Computing $y(t_1)$ : commutativity (1)

$$y(t) = \int x(v)h(t-v) dv$$

$$= \int \delta(v-t_1+1)h(t-v) dv$$

$$+ \int \delta(v-t_1+.5)h(t-v) dv$$

$$+ \int \delta(v-t_1)h(t-v) dv$$

$$\rightarrow h(t-t_1+1) \leftarrow$$

$$\rightarrow h(t-t_1+.5) \leftarrow$$

$$\rightarrow h(t-t_1) \leftarrow$$

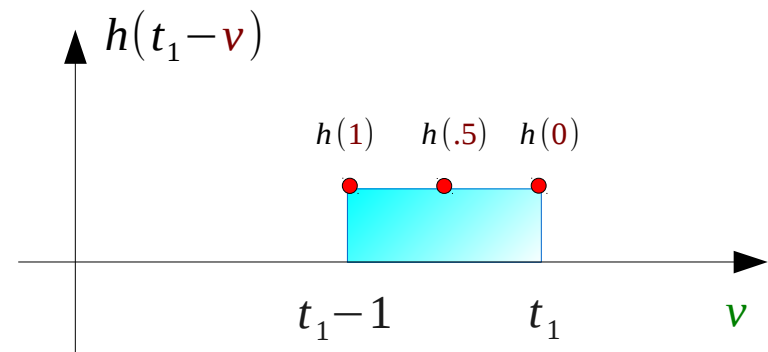
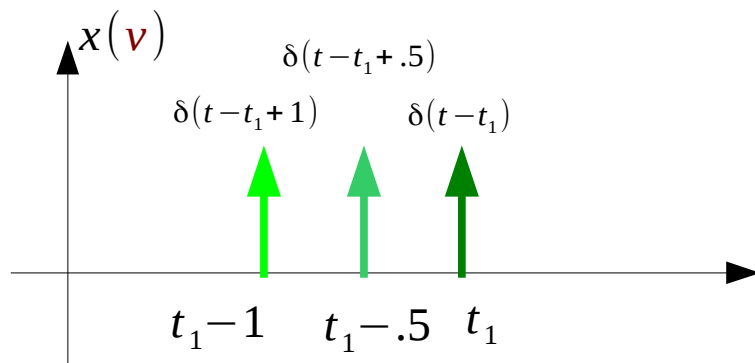
$$y(t) = \int x(t-v)h(v) dv$$

$$= \int \delta(t-v-t_1+1)h(v) dv$$

$$+ \int \delta(t-v-t_1+.5)h(v) dv$$

$$+ \int \delta(t-v-t_1)h(v) dv$$

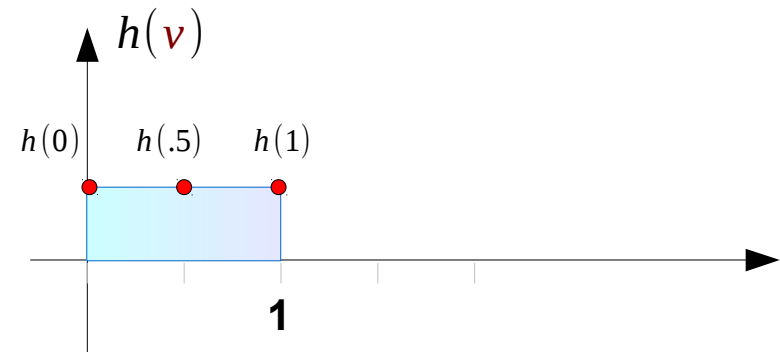
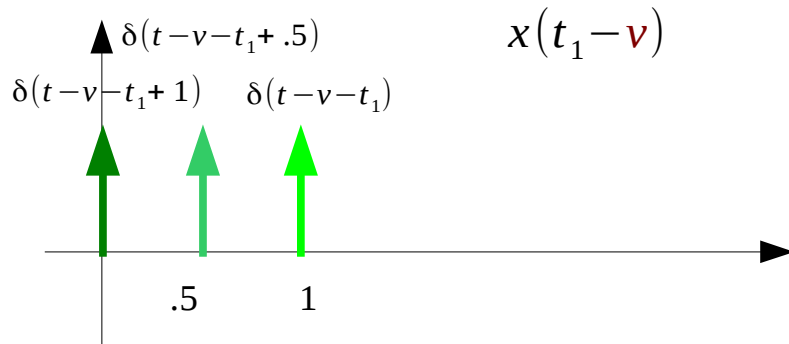
## Flip and Shift $h(t)$



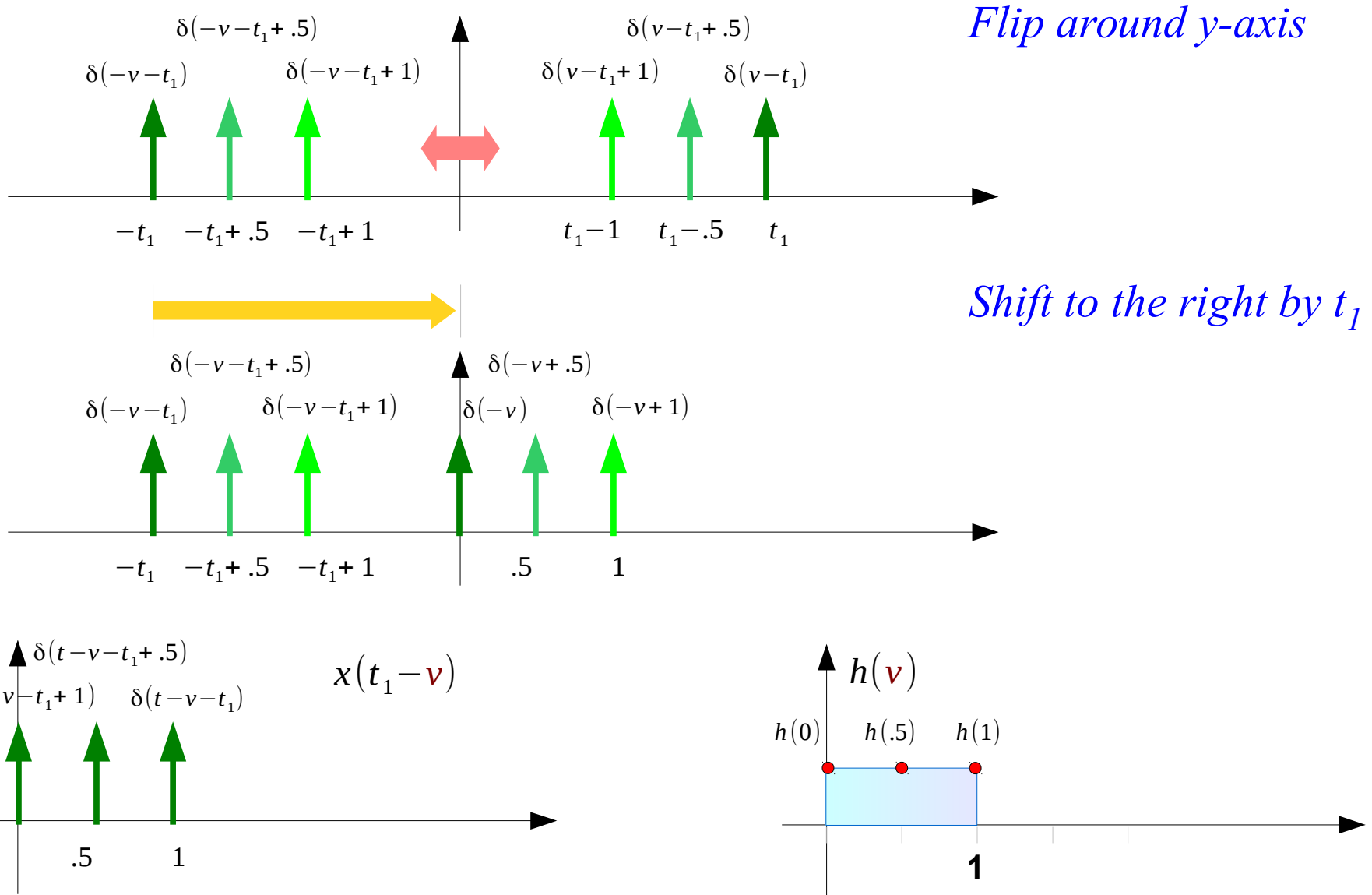
# Computing $y(t_1)$ : commutativity (2)

$y(t) = \int x(v)h(t-v) dv$ $= \int \delta(v-t_1+1)h(t-v) dv$ $+ \int \delta(v-t_1+.5)h(t-v) dv$ $+ \int \delta(v-t_1)h(t-v) dv$	$\rightarrow h(t-t_1+1) \leftarrow$ $\rightarrow h(t-t_1+.5) \leftarrow$ $\rightarrow h(t-t_1) \leftarrow$	$y(t) = \int x(t-v)h(v) dv$ $= \int \delta(t-v-t_1+1)h(v) dv$ $+ \int \delta(t-v-t_1+.5)h(v) dv$ $+ \int \delta(t-v-t_1)h(v) dv$
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Flip and shift input  $x(t)$

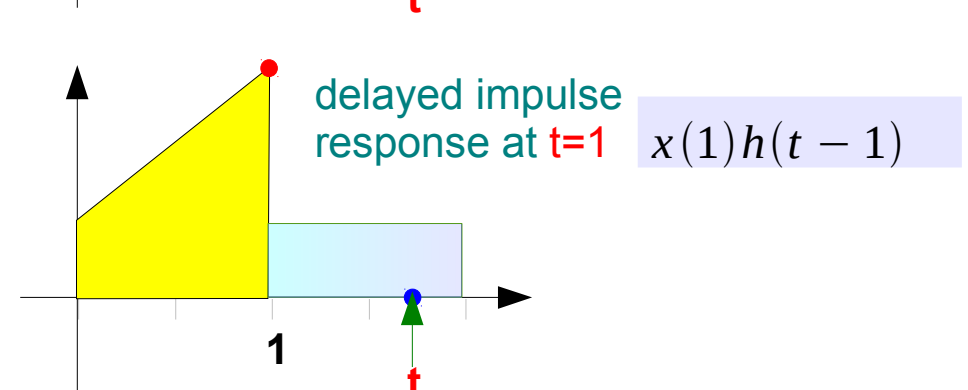
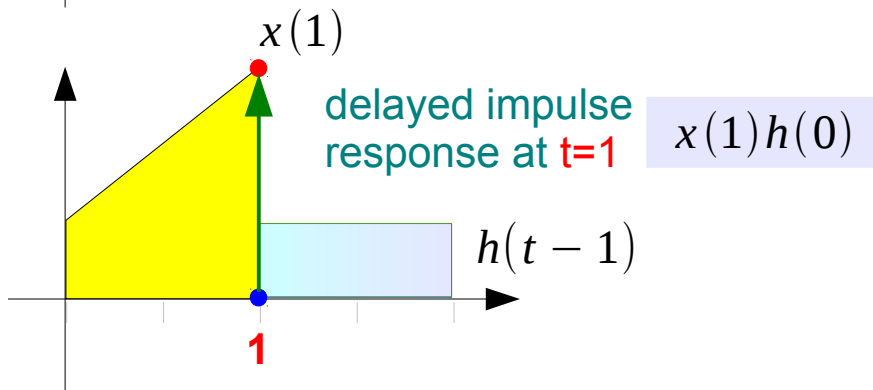
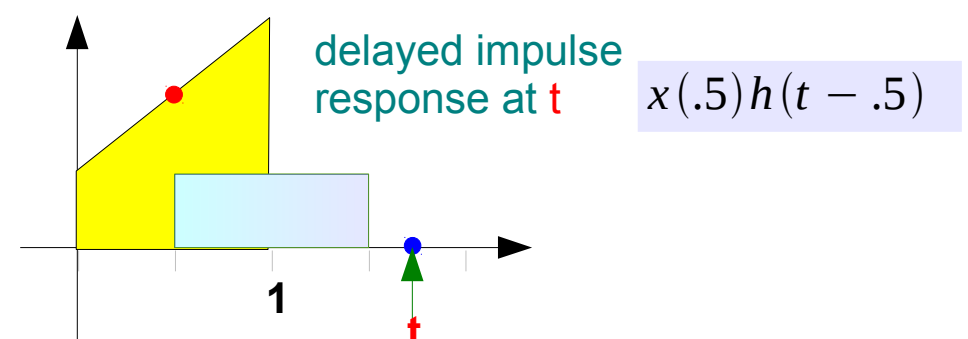
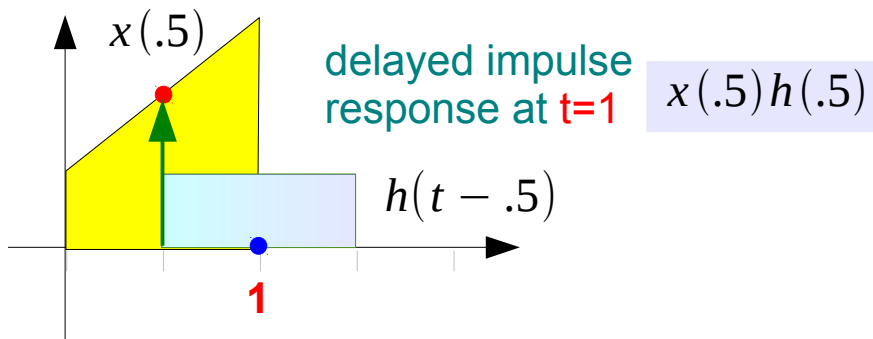
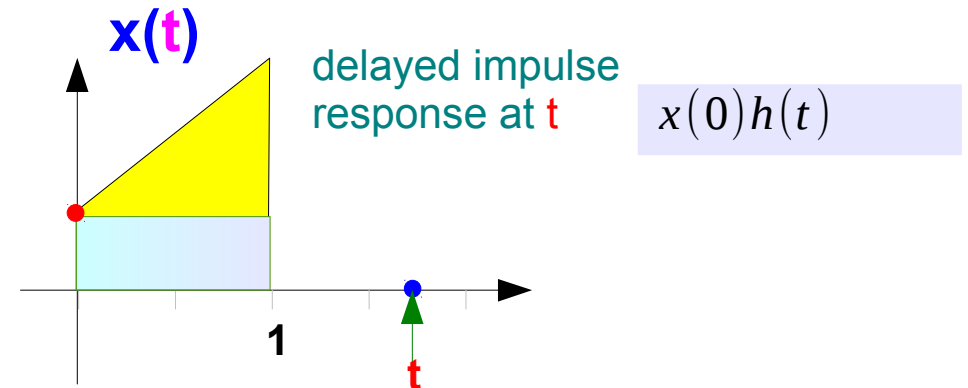
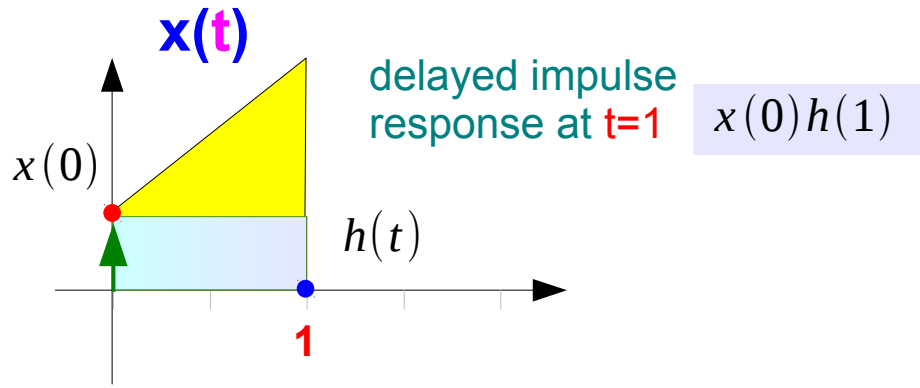


# Computing $y(t_1)$ : commutativity (3)

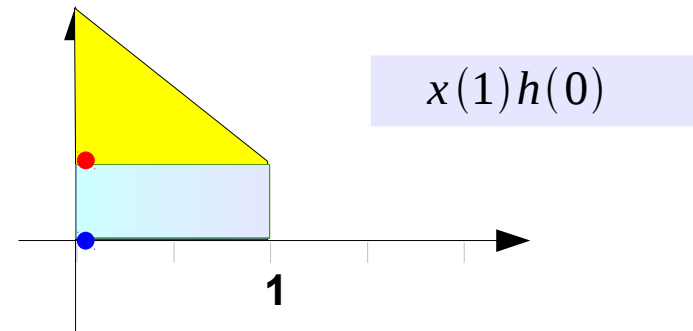
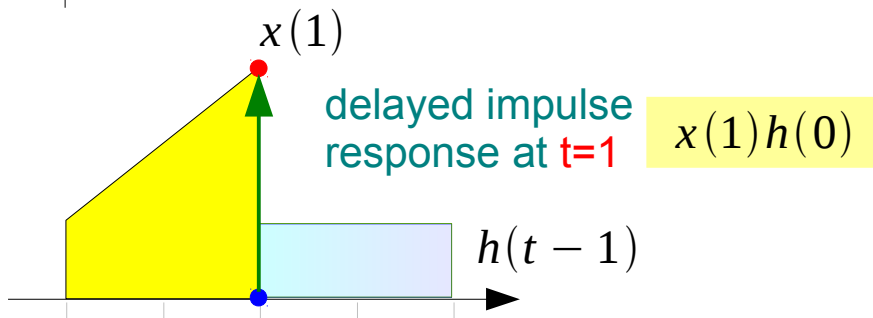
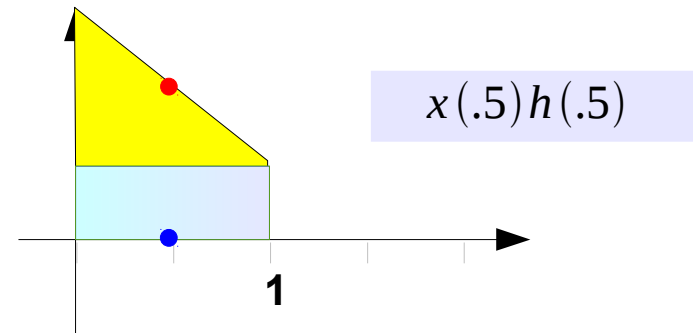
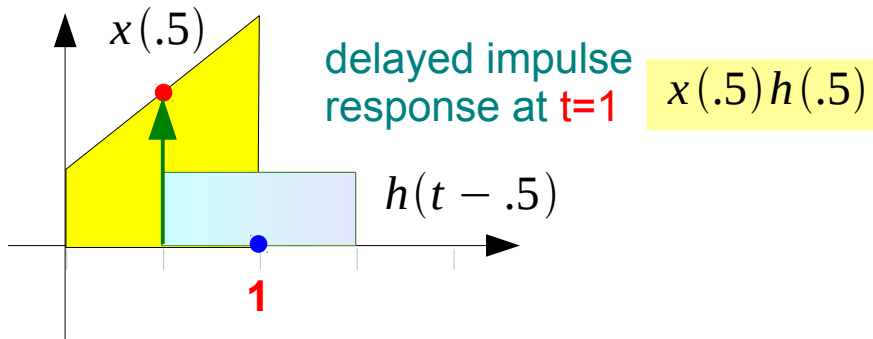
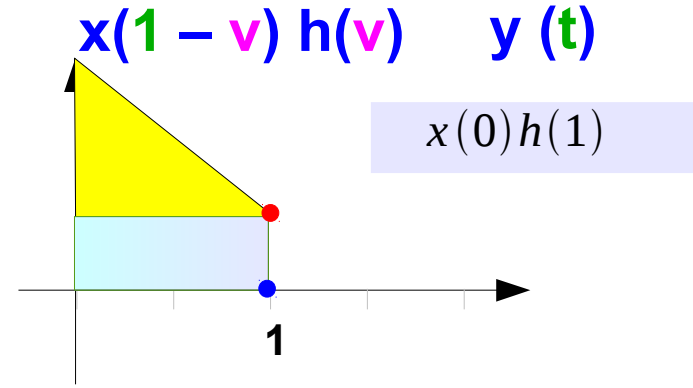
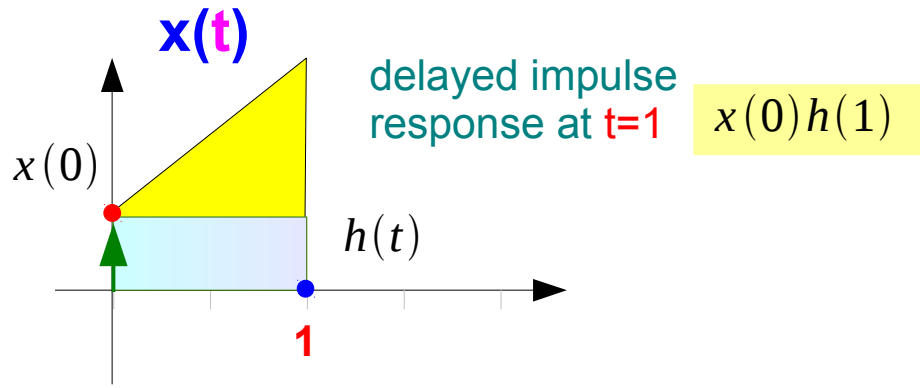




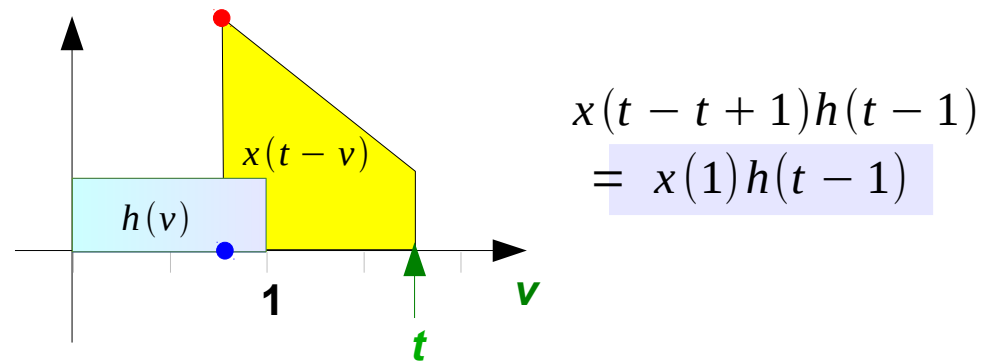
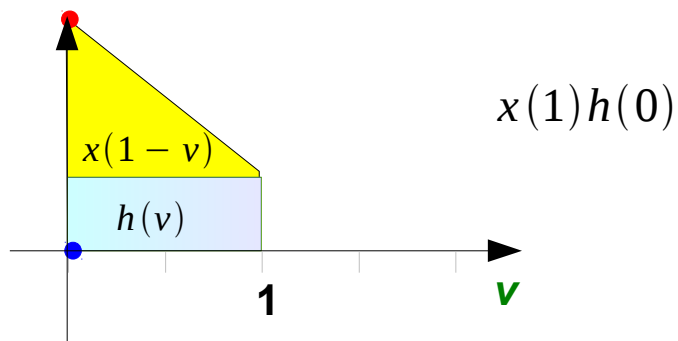
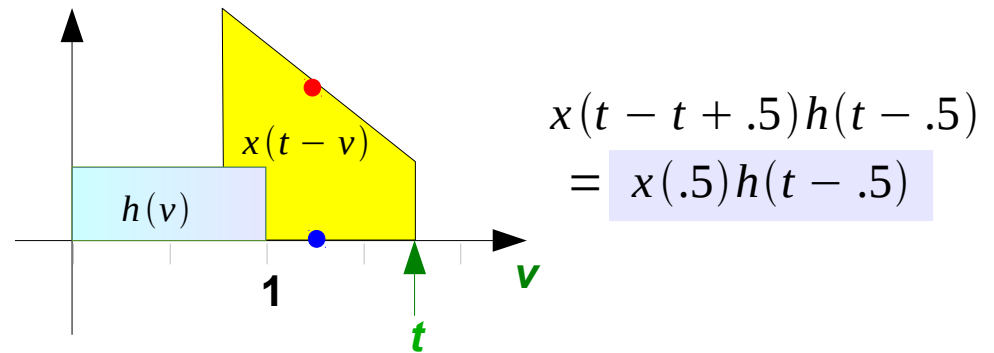
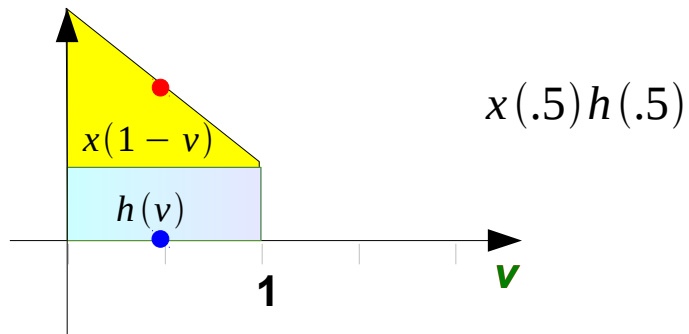
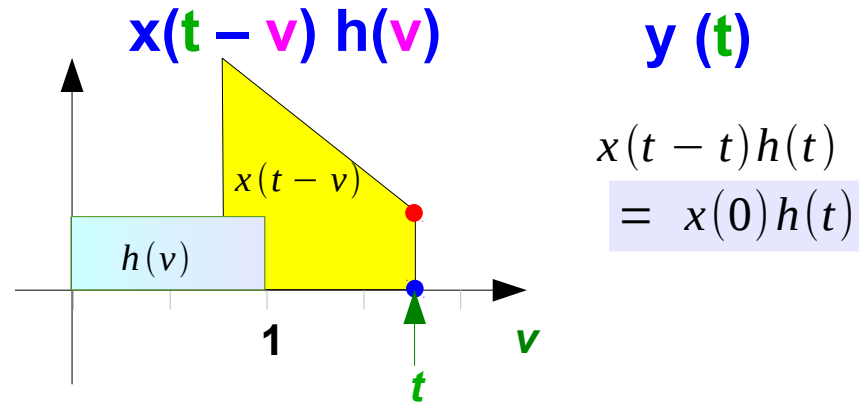
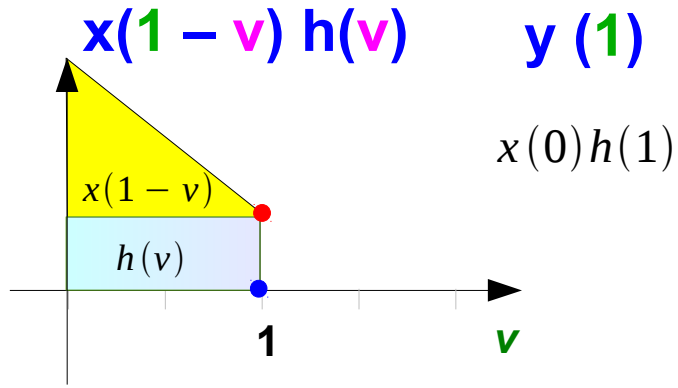
# Computing $y(1)$ , $y(t)$



# Computing $y(1)$ : shift & flip $x(t)$

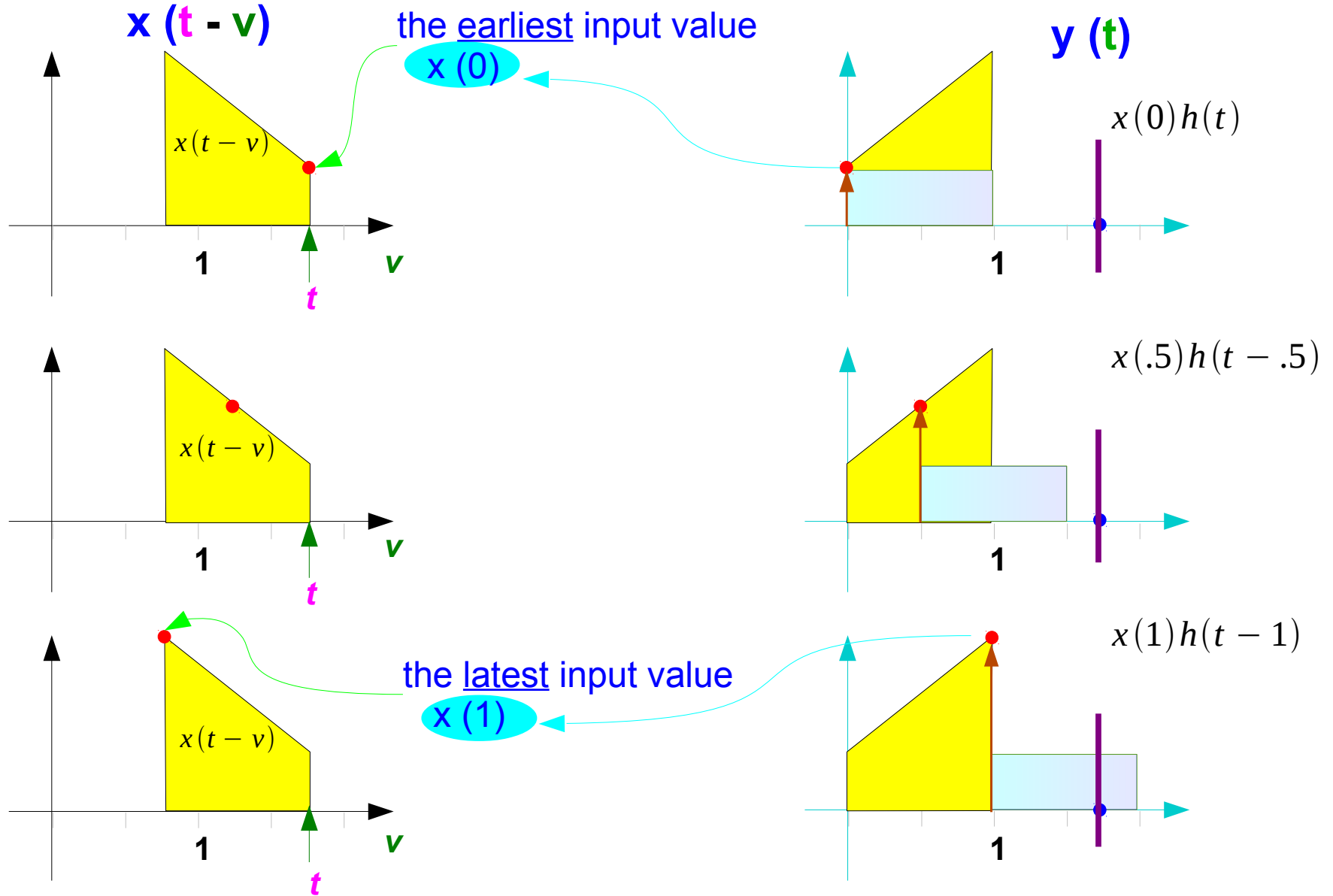


# Computing $y(t)$ : shift & flip $x(t)$

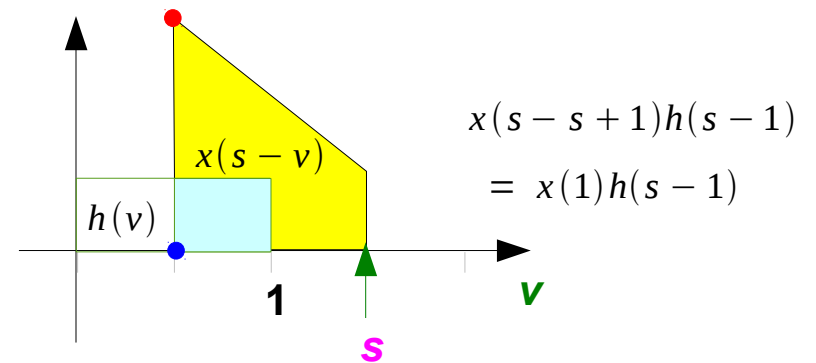
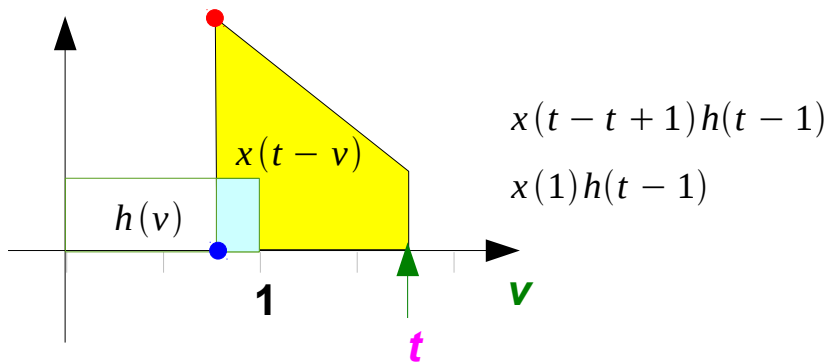
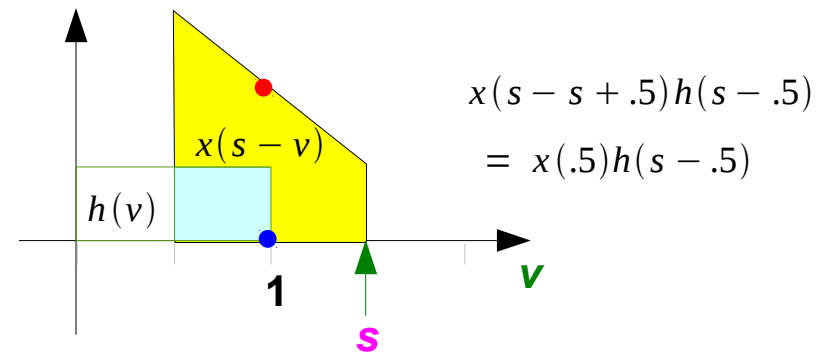
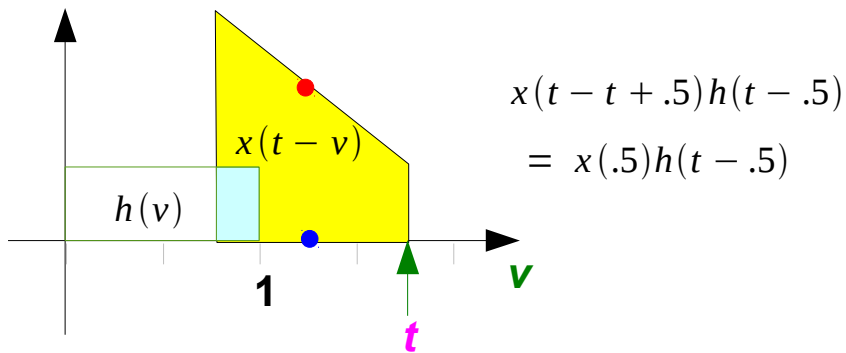
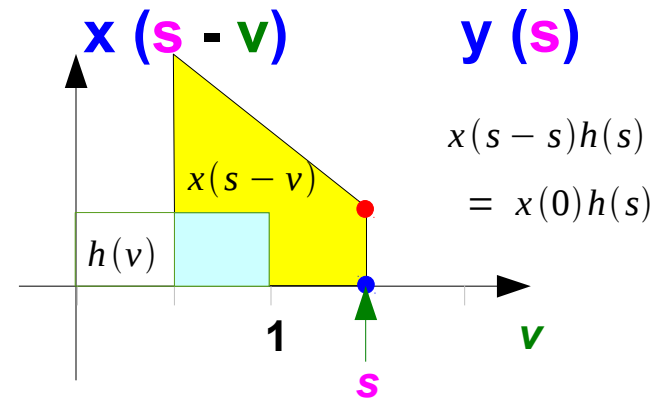
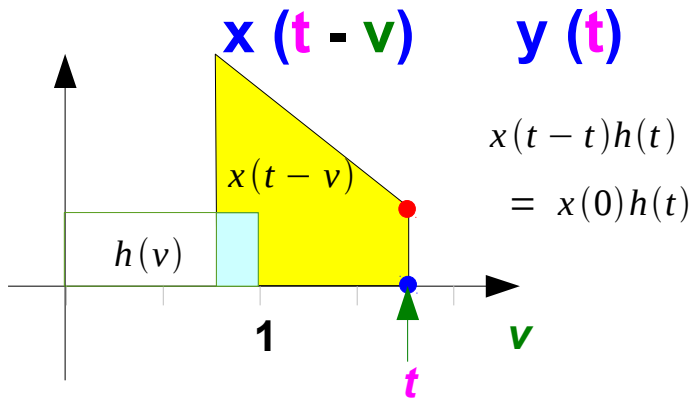




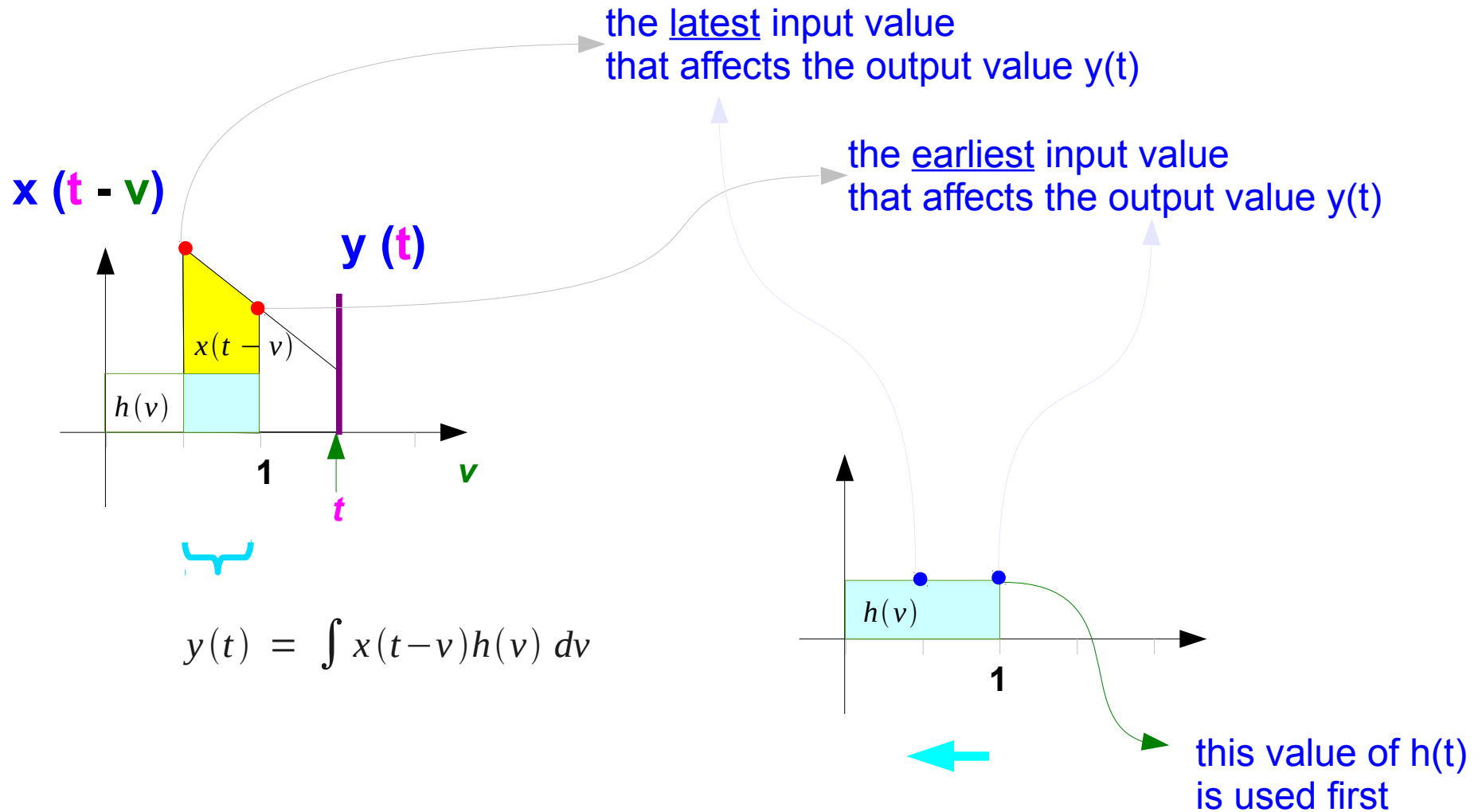
# Computing $y(t)$ : the earliest and latest inputs



# Computing $y(t)$ , $y(s)$

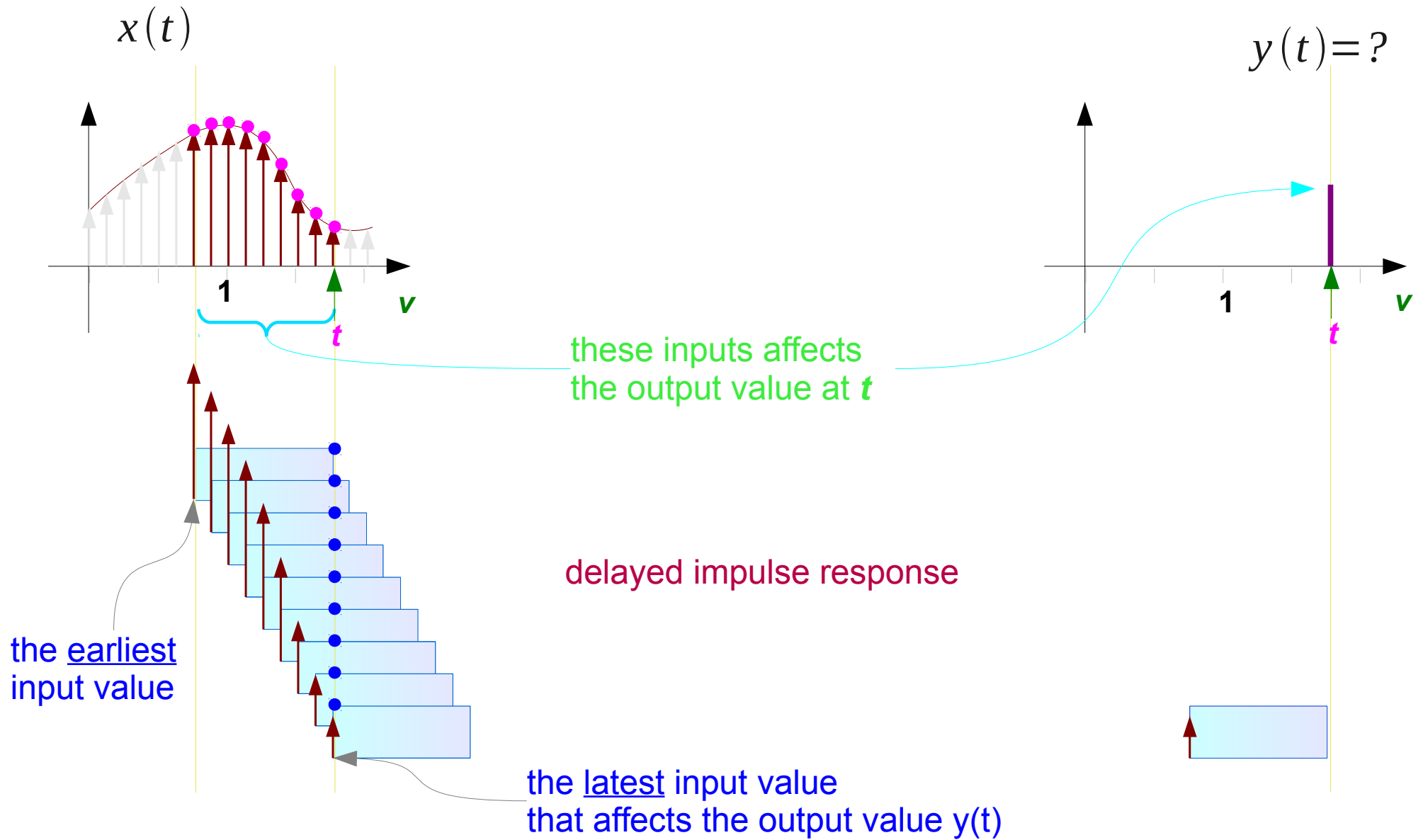


# Computing $y(t)$ : earliest and latest inputs

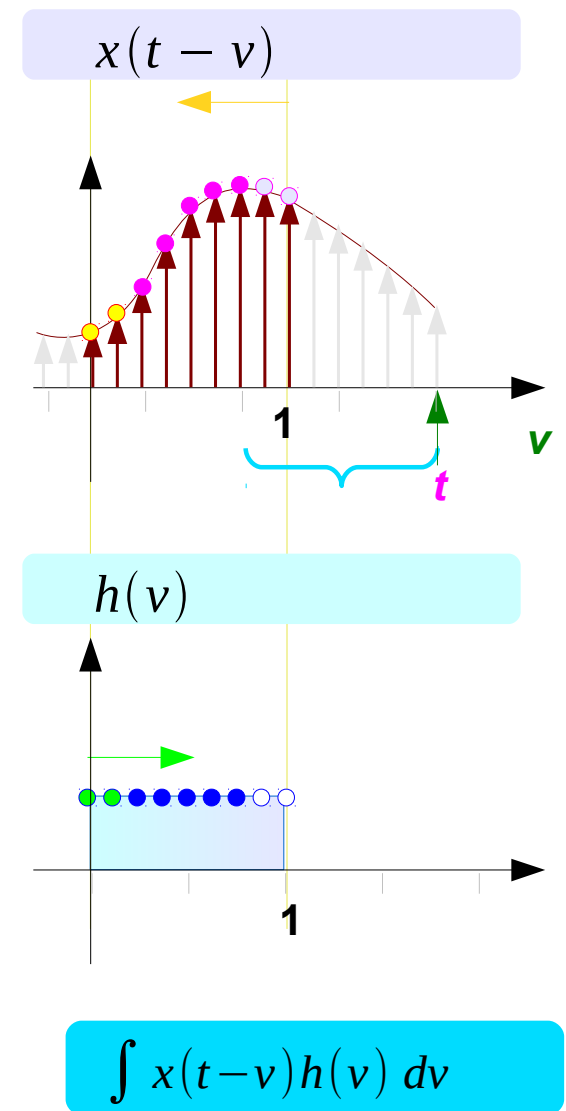
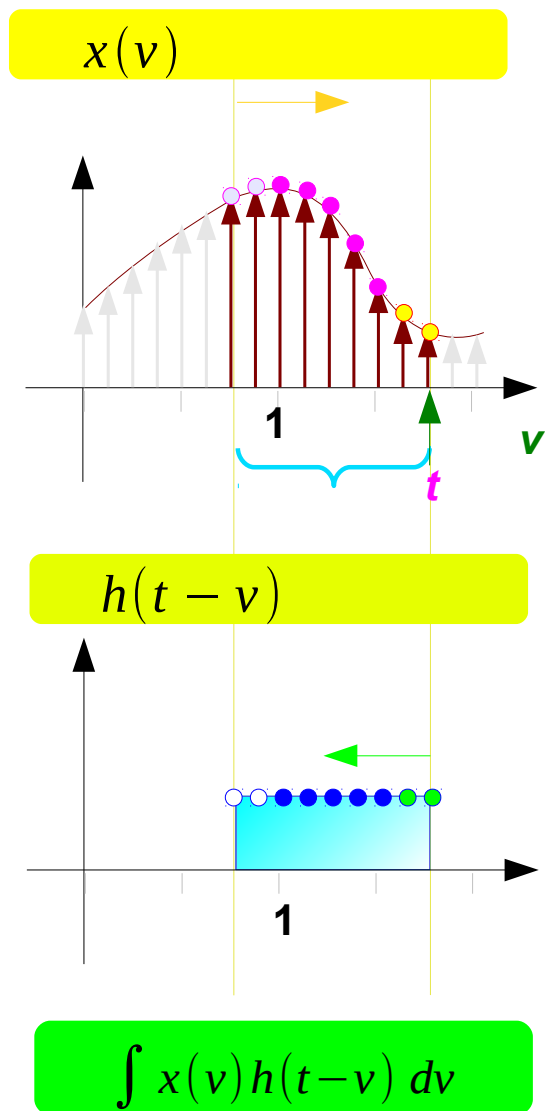
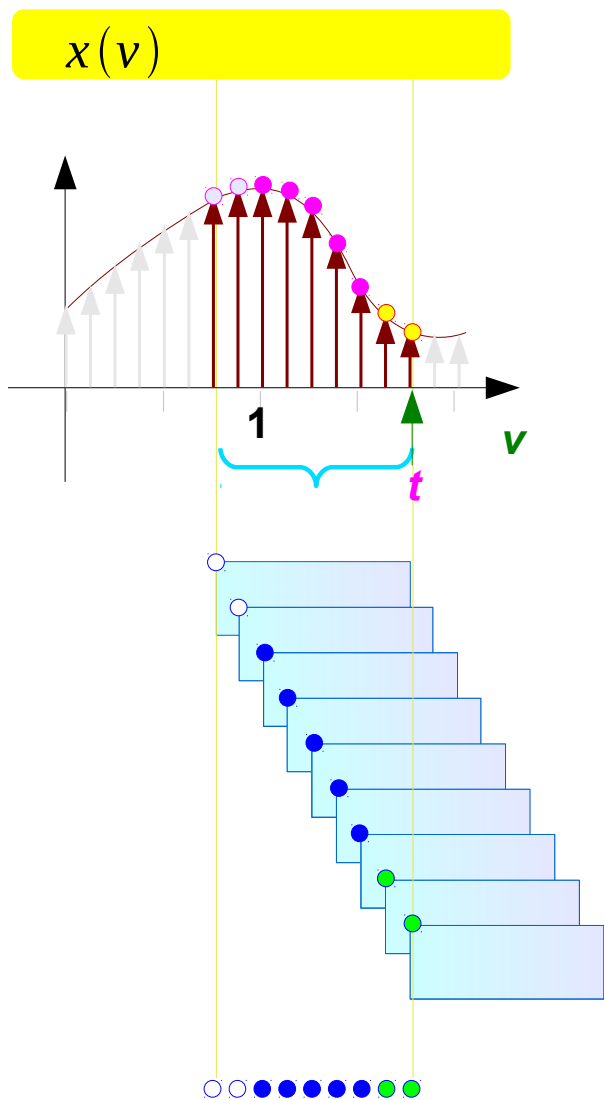




# Computing $y(t)$ : delayed impulse response



# Computing $y(t)$ : multiplication sequence



## References

- [1] <http://en.wikipedia.org/>
- [2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003